

Main Ideas in Class Today

You should be able to:

- Compute center of gravity
- Understand why some things are more difficult to rotate
- Utilize the **rotational equivalent** to conservation of (**angular**) momentum
- Understand Moment of Inertia, Rotational Kinetic Energy and Angular Momentum

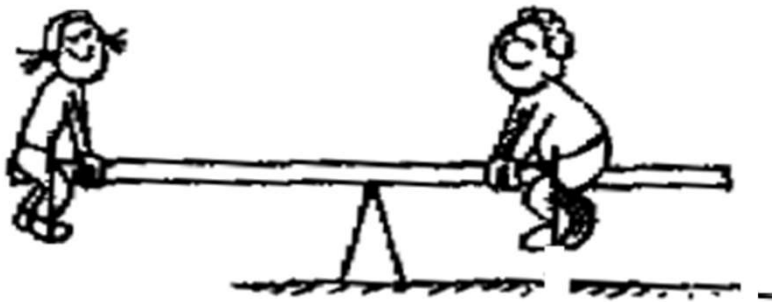
Extra Practice: 8.39, 8.43, 8.49, 8.53, 8.55, 8.57, 8.61, 8.63, 8.73, 8.85

60
kg

15 kg



Find the center of gravity of the system of two blocks above if they are 50 m apart.

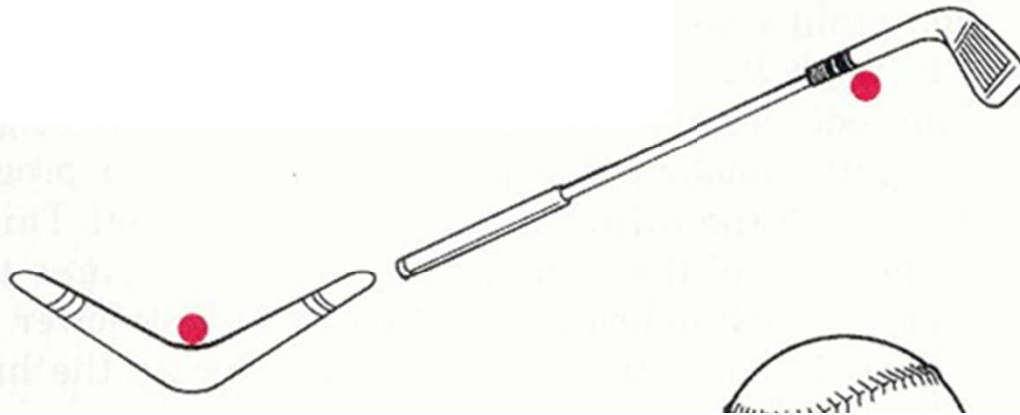
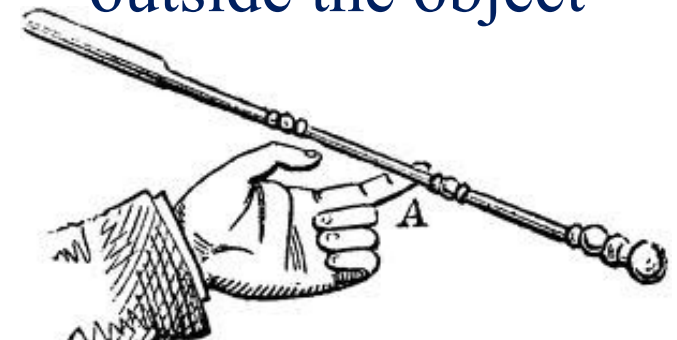


Center of Gravity/Mass

The center of gravity is the point around which a body's mass is equally distributed in all directions.

In a uniform object, at its mid point

Center of gravity can be outside the object



$$x_{cg} = \frac{m_1 x_1 + m_2 x_2 + m_3 x_3 + \dots}{m_1 + m_2 + m_3 + \dots} = \frac{\sum m_i x_i}{\sum m_i}$$

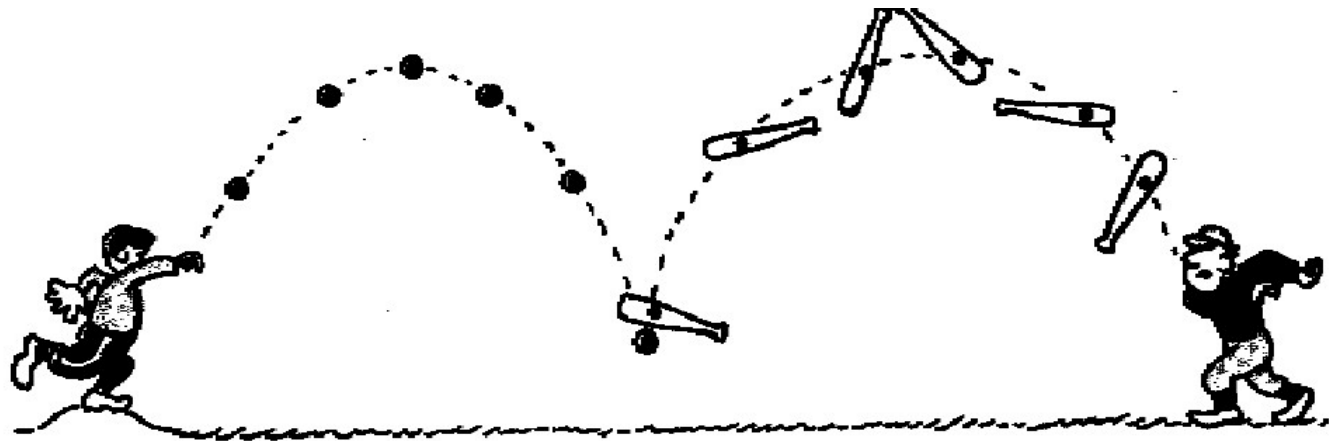
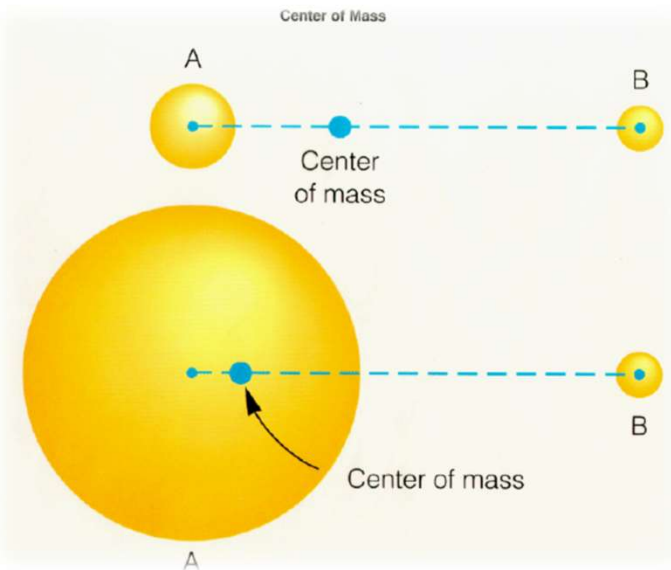
Center of Mass in Astrophysics

Even star/planet systems rotate about center of mass

Center of mass of solar system is not in the center of the star, causing the star to wobble a little

Astronomers search for wobbling stars to find planets

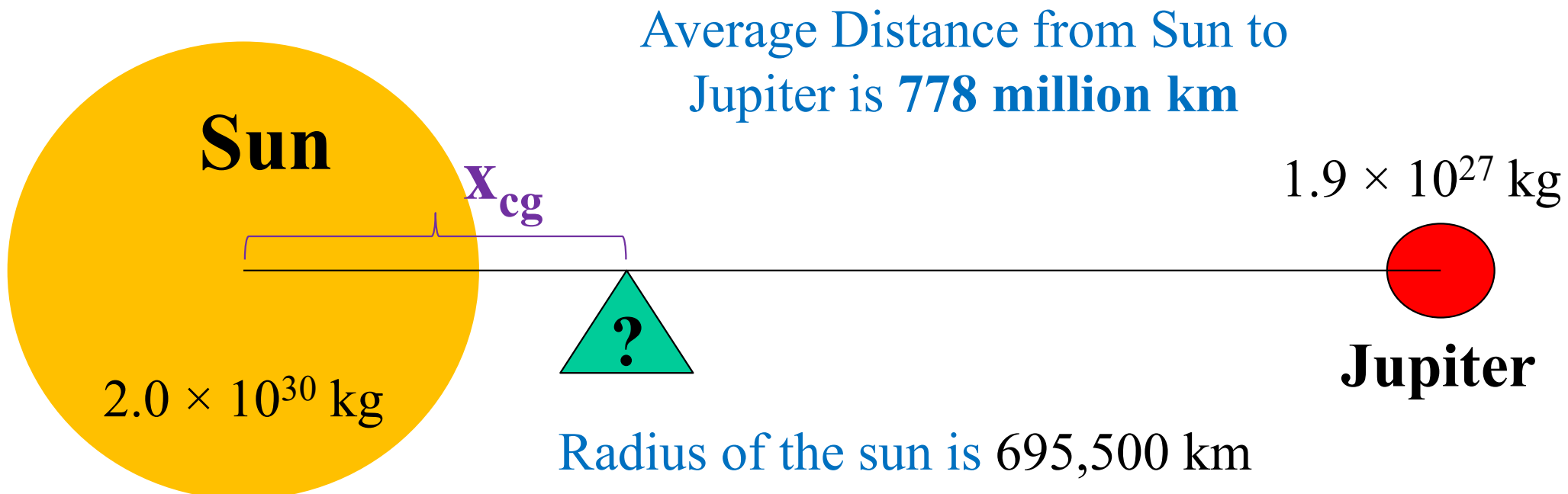
As of October 2024, over 5600 extrasolar planets have been confirmed.



Center of Mass in Astrophysics

Star/planet systems (and other objects) rotate about center of mass

Imagine if our solar system only consisted of the Sun and Jupiter. Where would the center of mass be?

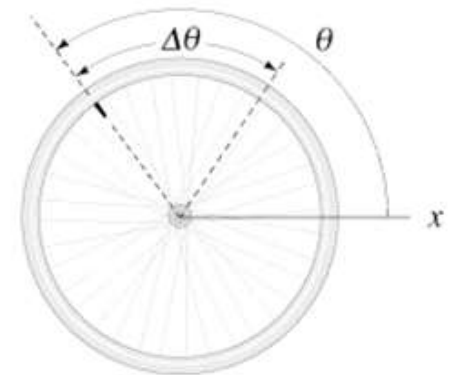


Everything has a rotational equivalent

What formulas do we still need to look at the equivalents of?

Ch. 4 Forces, Ch. 5 Energy, Ch. 6 Momentum

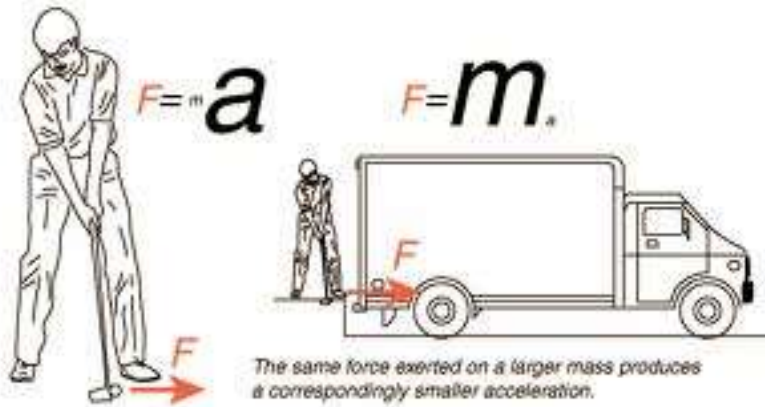
Linear		Rotational	
Δx		$\Delta \theta$	$\Delta x = r \Delta \theta$
$\bar{v} = \frac{\Delta x}{\Delta t}$	Note the line means average!	$\bar{\omega} = \frac{\Delta \theta}{\Delta t}$	$v = r \omega$
$\bar{a} = \frac{\Delta v}{\Delta t}$		$\bar{\alpha} = \frac{\Delta \omega}{\Delta t}$	$a = r \alpha$
For constant a :		For constant α :	
$v = v_o + at$	If the radius does not change	$\omega = \omega_o + \alpha t$	
$\Delta x = v_o t + \frac{1}{2} at^2$		$\Delta \theta = \omega_o t + \frac{1}{2} \alpha t^2$	
$v^2 = v_o^2 + 2a \Delta x$		$\omega^2 = \omega_o^2 + 2\alpha \Delta \theta$	



Moment of Inertia

- An object's mass tells us how difficult it is to push by the formula:

$$\Sigma F = ma \text{ (Newton's 2}^{\text{nd}} \text{ law)}$$



- An object's **moment of inertia (I)** tells us how difficult it is to rotate by the formula $\Sigma \tau = I\alpha$

where α = angular acceleration





Rotational Inertia

$$\Sigma\tau = I\alpha$$



The angular velocity of an object does not change ($\alpha=0$) unless acted on by a torque

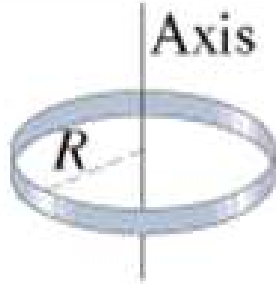
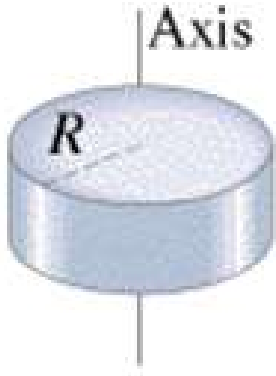
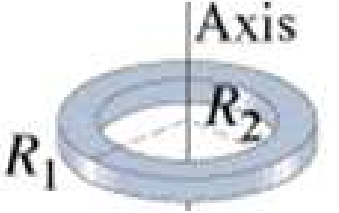
Compare to Newton's 1st law: **The velocity of an object does not change ($a=0$) unless acted on by a force** $\Sigma F = ma$



Rotational Inertia depends not just **on mass but** also how the mass is distributed



Examples

Object		Location of axis		Moment of inertia
Thin hoop of radius R	A	Through center		MR^2
Solid cylinder of radius R	B	Through center		$\frac{1}{2}MR^2$
Hollow cylinder of inner radius R_1 and outer radius R_2	C	Through center		$\frac{1}{2}M(R_1^2 + R_2^2)$ $R_1 \neq R_2$

If the mass and outer R is the same, which one of these 3 I 's is smallest?



Do not memorize, will be given if needed

$$I = \Sigma MR^2$$

D. Two are the same

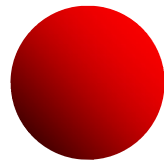
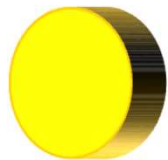
Q108

All shapes below have the same mass and same radius

In order to **maximize** the moment of inertia (I), the mass should be:

$I = MR^2$ $\frac{1}{2} MR^2$ $\frac{2}{5} MR^2$

Hoop Disk Sphere



- A. Concentrated at the edges
- B. Evenly distributed
- C. Concentrated at the center
- D. Makes no difference



Q109

Race of the Geometrical Shapes

All shapes below have the same mass and same radius

Since all of these shapes have the **same mass**, they all have the same force that will act to accelerate them down the incline (torque).

Which shape will win the race?

A. Hoop

B. Disk

C. Sphere

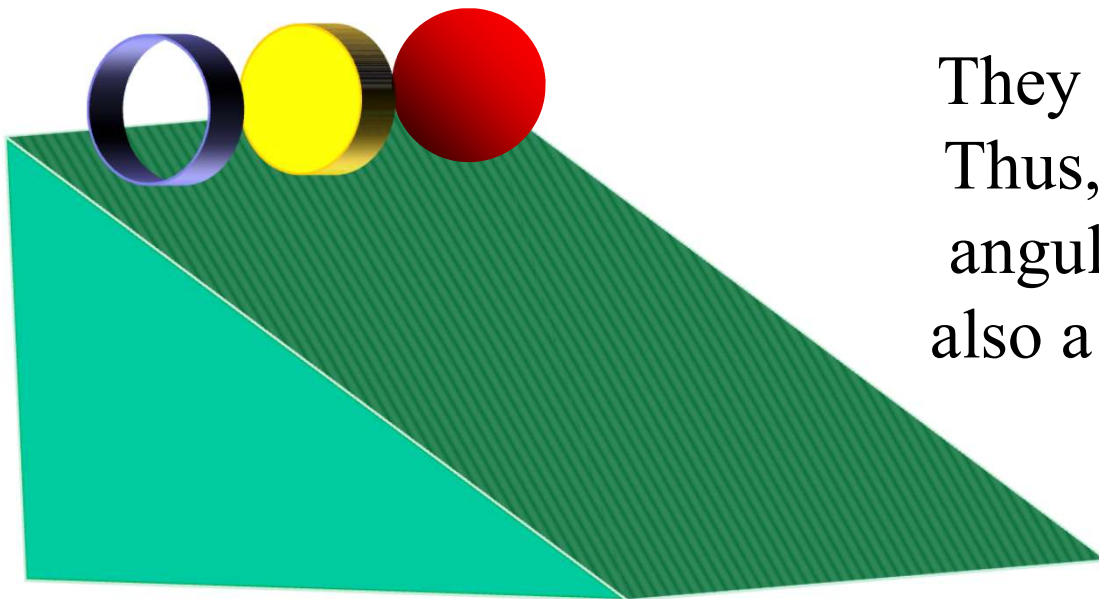
D. All same

$$I = MR^2 \quad \frac{1}{2} MR^2 \quad \frac{2}{5} MR^2$$

Hoop Disk Sphere

$$\Sigma \tau = I\alpha$$

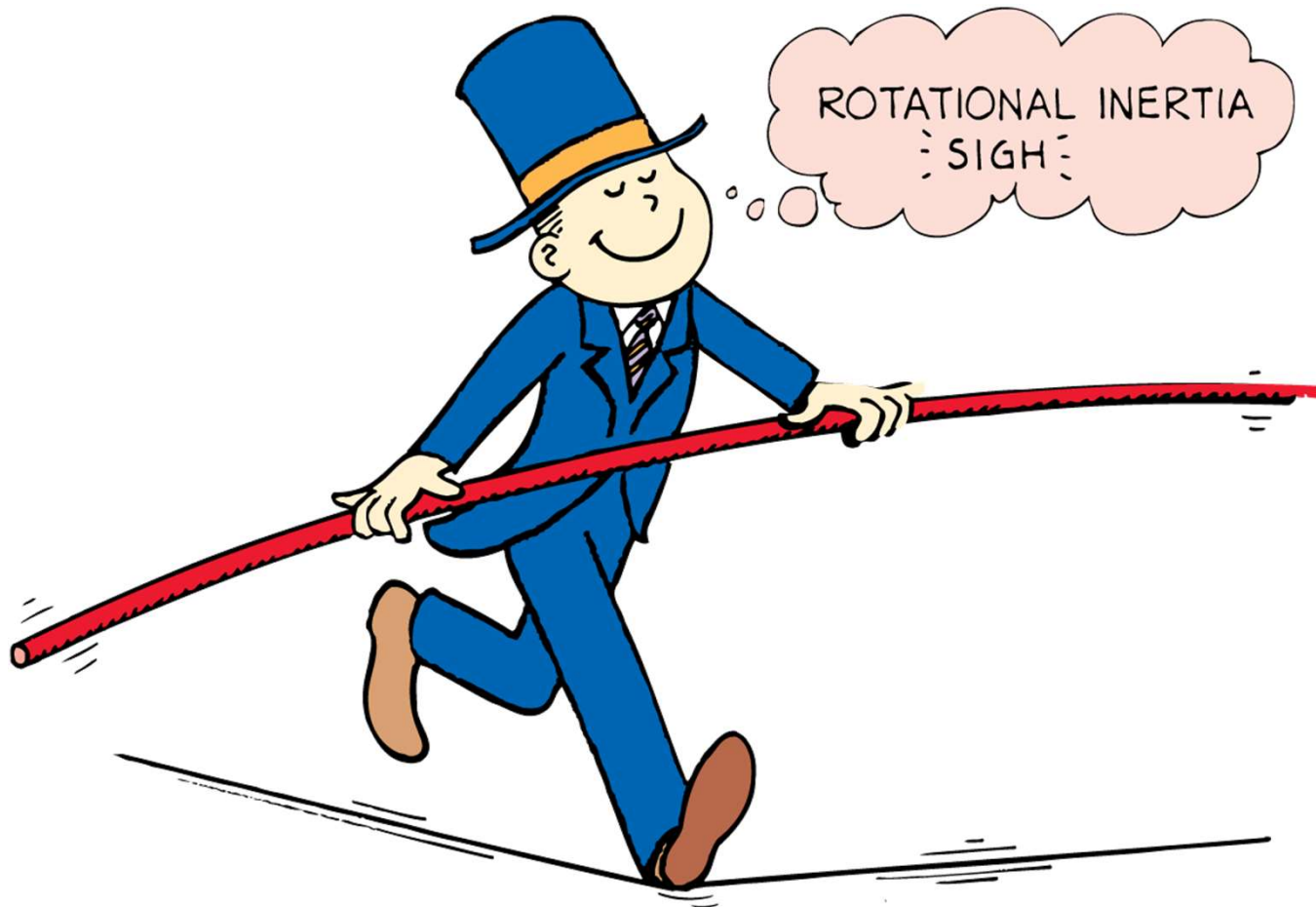
They all have the same torque.
Thus, smaller I means a larger angular acceleration, which is also a larger linear acceleration



Q110

Rotational Inertia

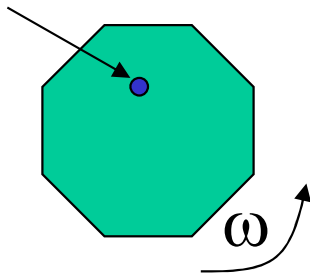
By holding a long pole, the tightrope walker increases his rotational inertia, making it easier for him to balance (not turning).



Rotational Kinetic Energy

- Energy of rotation of a solid body

axis of rotation



Kinetic energy is sum of kinetic energies of all particles making up the body:

$$KE = \sum \left(\frac{1}{2} m v^2 \right)$$

$$v = r \omega$$

$$KE = \sum \left(\frac{1}{2} m r^2 \omega^2 \right) = \frac{1}{2} \sum \left(m r^2 \right) \omega^2$$

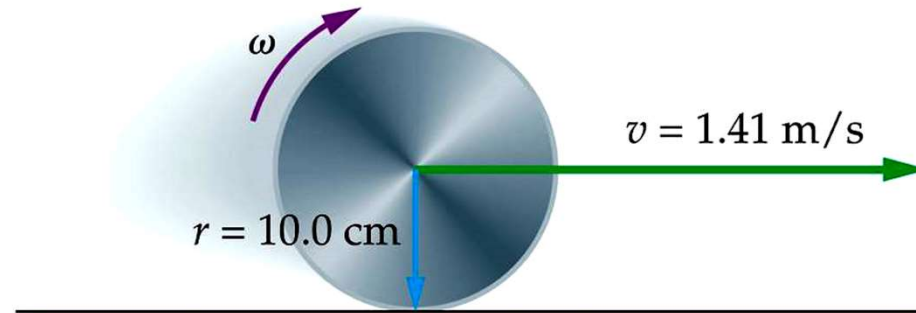
$$I = \sum \left(m r^2 \right)$$



$$\text{Rotational KE} = \frac{1}{2} I \omega^2$$

Like a Rolling Disk

It requires extra energy to rotate things!



A 1.20 kg disk with a radius of 10.0 cm rolls without slipping. The linear speed of the disk is $v = 1.41 \text{ m/s}$.

- Find the translational kinetic energy.
- Find the rotational kinetic energy.
- Find the total kinetic energy.

**Keep in mind for
conservation of
energy problems.**

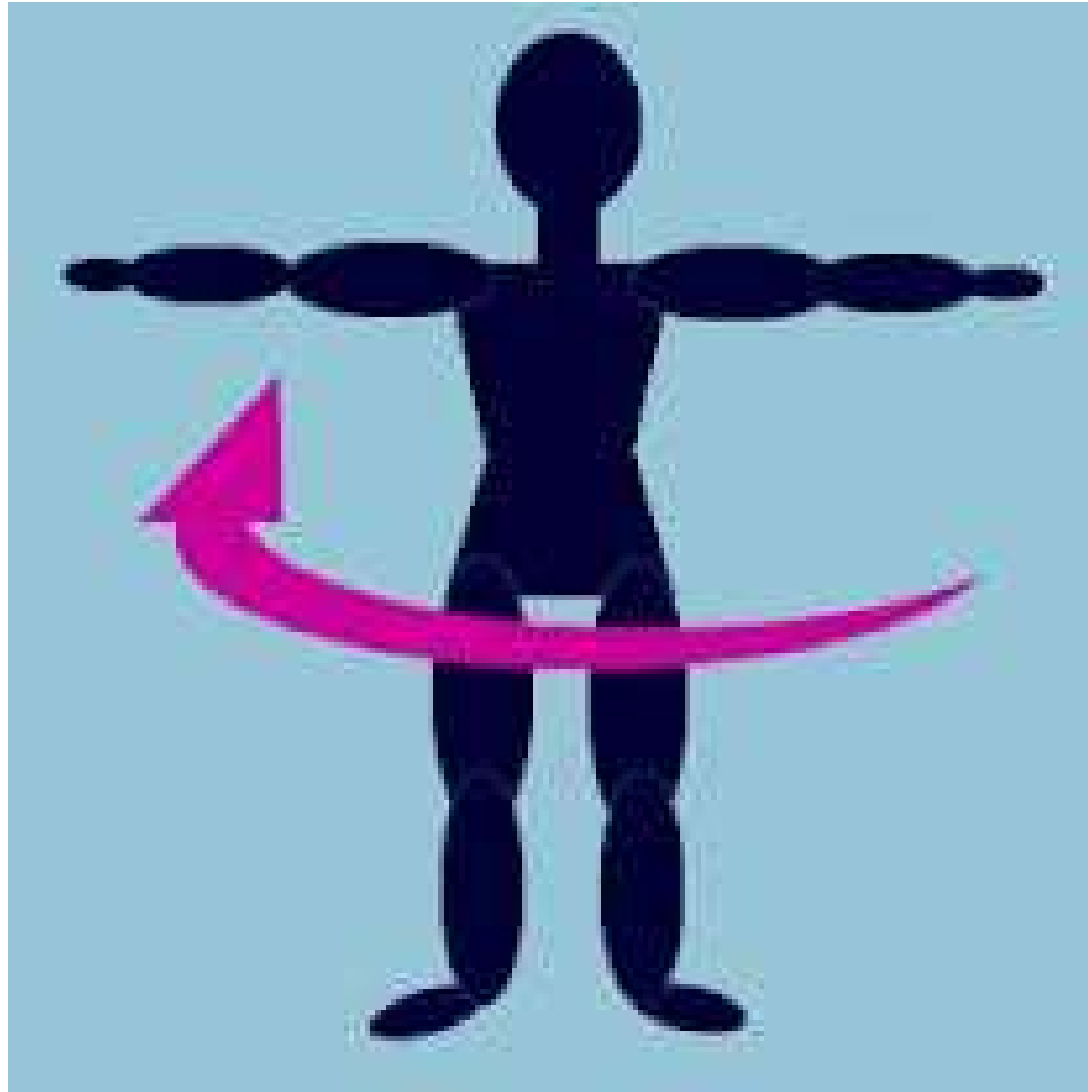
$$K_t = \frac{1}{2} m v^2 = \frac{1}{2} (1.20 \text{ kg})(1.41 \text{ m/s})^2 = 1.19 \text{ J}$$

$$K_r = \frac{1}{2} I \omega^2 = \frac{1}{2} \left(\frac{1}{2} m r^2 \right) (v / r)^2 = \frac{1}{4} (1.20 \text{ kg})(1.41 \text{ m/s})^2 = 0.595 \text{ J}$$

Note that the radius cancels out!

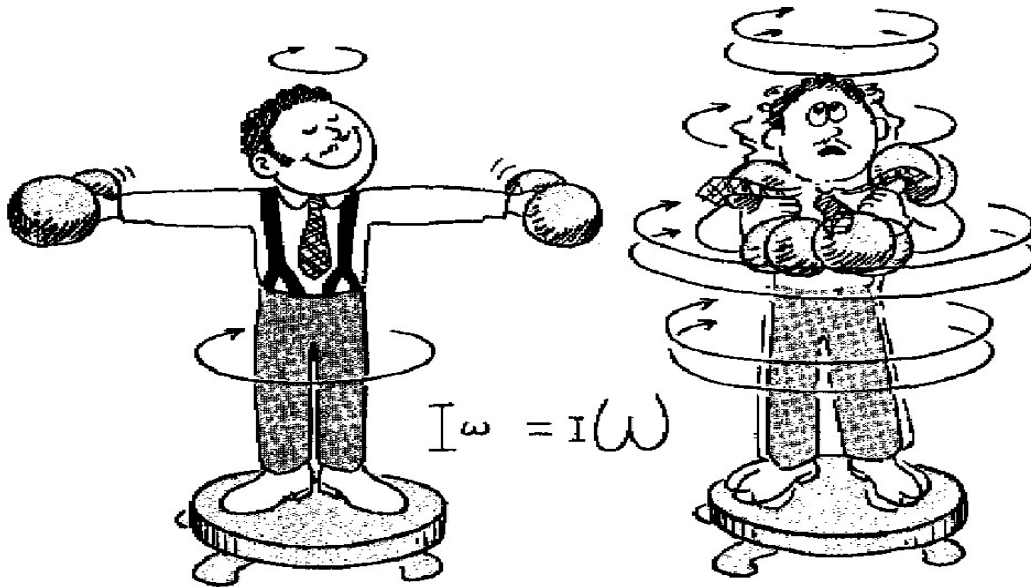
$$K_t + K_r = (1.19 \text{ J}) + (0.595 \text{ J}) = 1.79 \text{ J}$$

Stand Up and Space Yourself Out



What does it feel like is happening?

Conservation of Angular Momentum



Angular momentum $L = I\omega$

Spinning skater spins slowly with arms out, faster with arms in, faster yet with **arms up!**

Reducing r makes ω greater to have same angular momentum

$$I = \sum MR^2$$

Conservation of (Angular) Momentum

$$\vec{F}_{net} = \sum \vec{F} = \frac{\Delta \vec{p}}{\Delta t} = 0$$

If no unbalanced torque acts on a rotating system, the angular momentum of that system is constant



$$\tau_{net,system} = \sum \tau = \frac{\Delta L}{\Delta t} = 0$$

Angular momentum:

Makes the World Go Round (pun intended)

Relations

Linear Motion

Mass m

Linear velocity \mathbf{v}

Translational KE $\frac{1}{2}mv^2$

Linear momentum $\mathbf{p} = m\mathbf{v}$

$$\vec{F}_{net} = \sum \vec{F} = \frac{\Delta \vec{p}}{\Delta t}$$

($F=ma$)
when m constant

Rotational Motion

Moment of Inertia I

Angular velocity ω

Rotational KE $\frac{1}{2}I\omega^2$

Angular momentum $L = I\omega$

$$\tau_{net} = \sum \tau = \frac{\Delta L}{\Delta t}$$

Note: if I is constant, $\frac{\Delta L}{\Delta t} = \frac{I\omega - I\omega_o}{\Delta t} = \frac{I\Delta\omega}{\Delta t} = I\alpha$

I is likely to be constant than mass

A Windmill

In a light wind, a windmill experiences a constant torque of 255 N m.

If the windmill is initially at rest, what is its angular momentum after 2.00 s?

$$\tau = \frac{\Delta L}{\Delta t}$$



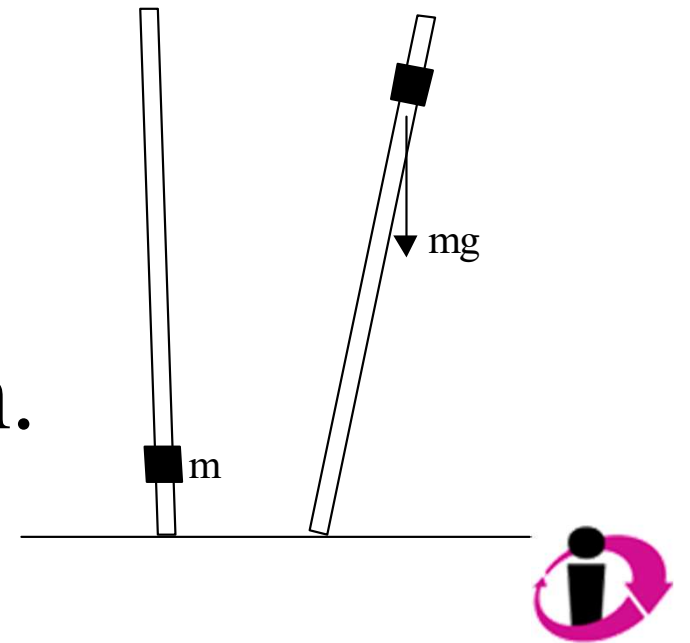
$$\Delta L = \tau \Delta t = (255 \text{ N})(2.00 \text{ s}) = 510 \text{ kg m}^2 / \text{s}$$

Notice that you do not need to know the moment of inertia of the windmill to do this calculation.

A mass m is attached to a long, massless rod. The mass is close to one end of the rod. Is it easier to balance the rod on end with the mass near the top or near the bottom?

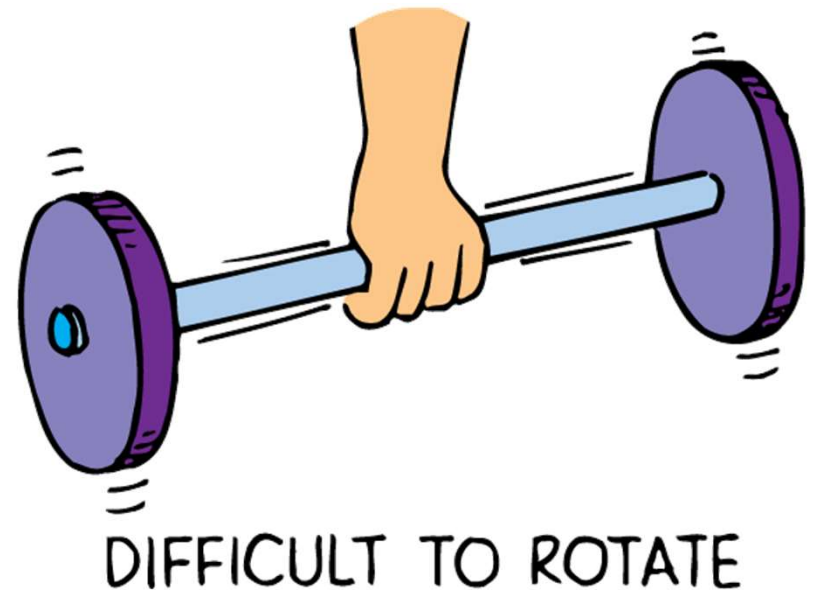
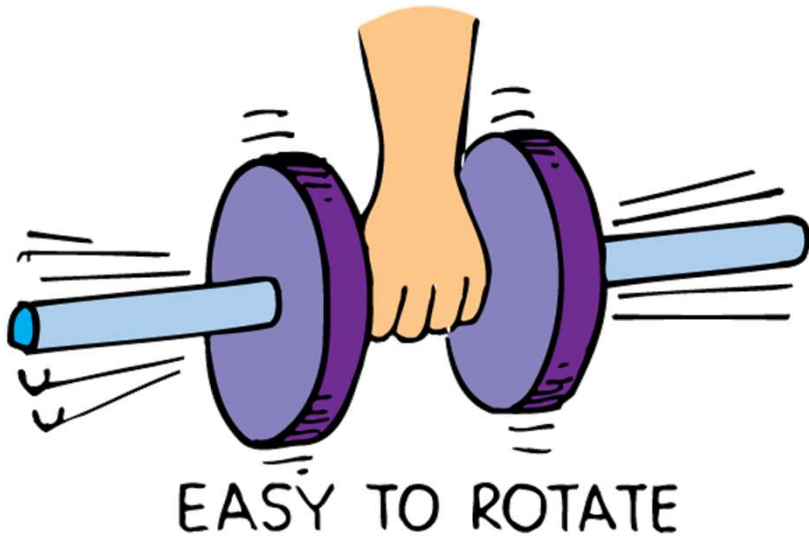
Hint: Small α means sluggish behavior and $\alpha = \frac{\tau}{I}$

- A: easier with mass near top.
- B: easier with mass near bottom.
- C: No difference.



Rotational Inertia

Rotational inertia depends on the distance of mass from the axis of rotation.



Race of the Geometrical Shapes

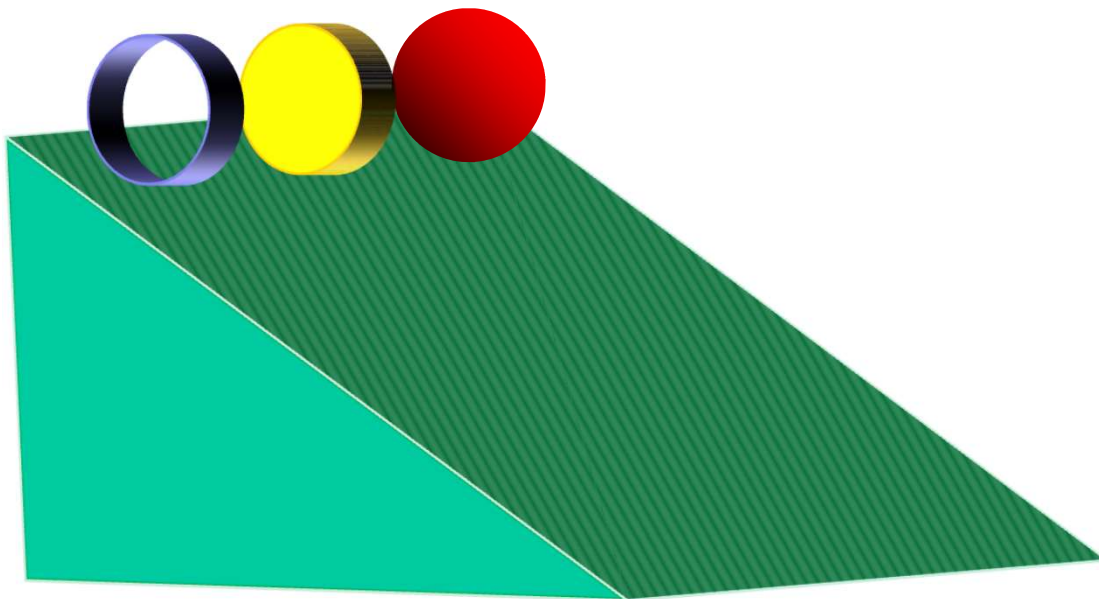
All shapes below have the same mass and same radius

Let's find the final velocities
of each of these shapes.

$$I = MR^2 \quad \frac{1}{2} MR^2 \quad \frac{2}{5} MR^2$$

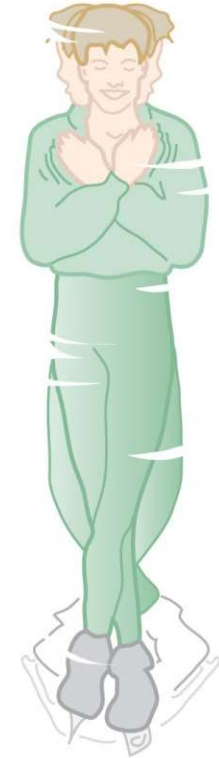
Hoop Disk Sphere

How would we do that?



How did we
do this with
blocks?

A spinning figure skater pulls his arms in as he rotates on the ice. As he pulls his arms in, what happens to his angular momentum L and kinetic energy K ?



- A. L and K both increase.
- B. L stays the same; K increases.
- C. L increases; K stays the same.
- D. L and K both stay the same.

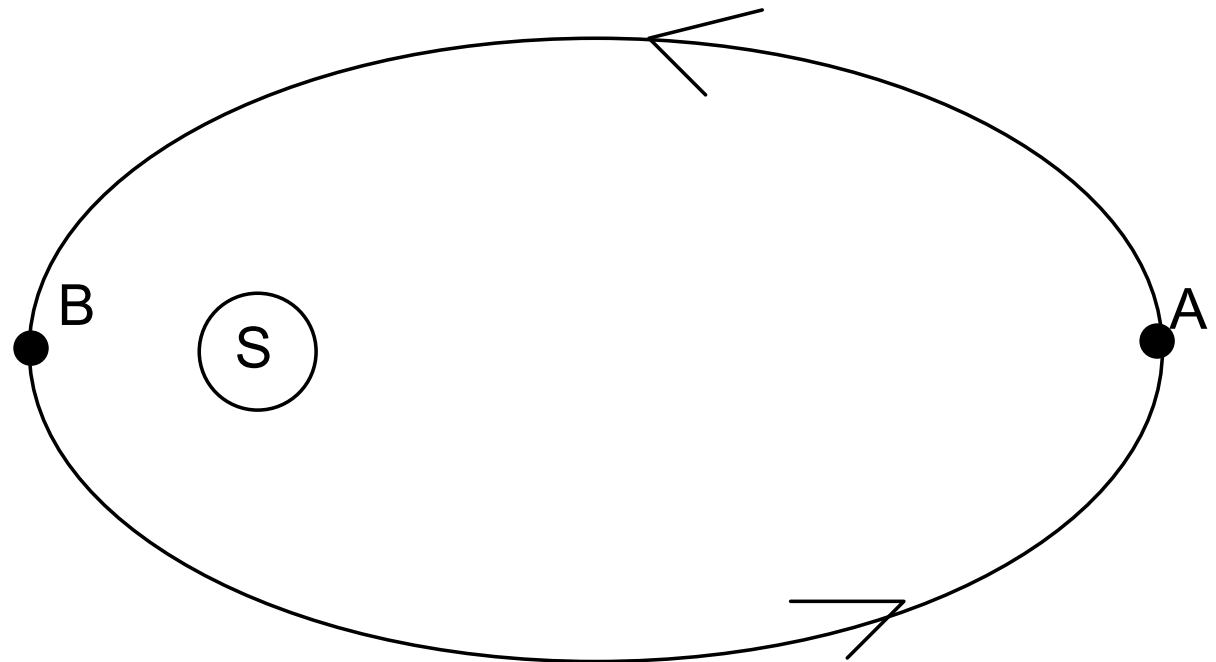


How does the magnitudes of the angular momentum of the planet L_{planet} (with the origin at the Sun) at positions A and B compare?

A: $L_A = L_B$

B: $L_A > L_B$

C: $L_A < L_B$



Rotational KE $\frac{1}{2} I \omega^2$

$I = \sum MR^2$

$$\frac{\Delta L}{\Delta t} = \frac{I\omega - I\omega_o}{\Delta t} = \frac{I\Delta\omega}{\Delta t} = I\alpha$$

Angular momentum $L = I\omega$

$$\tau_{net} = \sum \tau = \frac{\Delta L}{\Delta t}$$



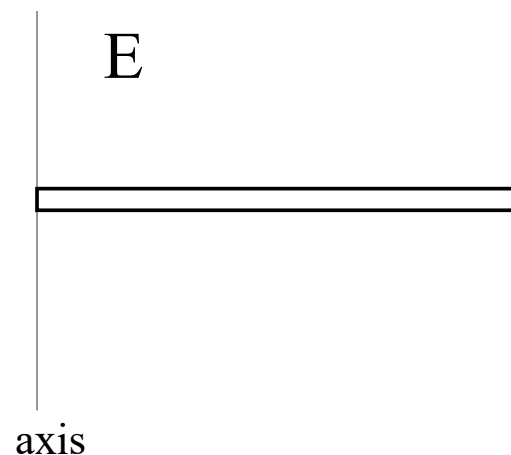
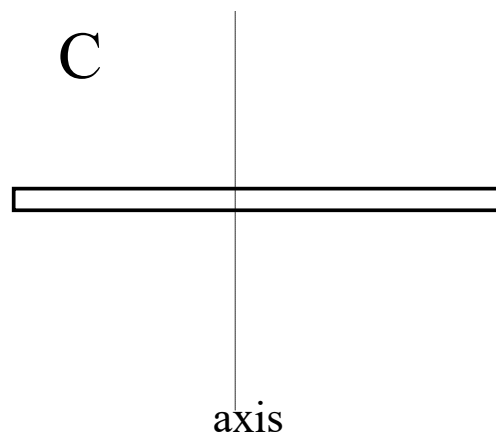
Q113

Consider a rod of uniform density with an axis of rotation through its center and an identical rod with the axis of rotation through one end. Which has the larger moment of inertia (more difficult to rotate)?

A: $I_C > I_E$

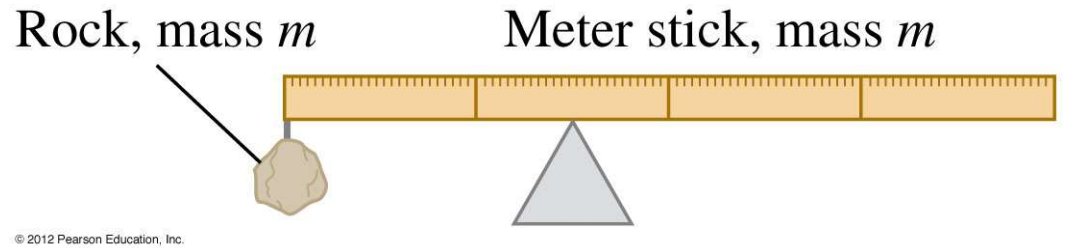
B: $I_C < I_E$

C: $I_C = I_E$



Q114

A rock is attached to the left end of a uniform meter stick that has the same mass as the rock. How far from the left end of the stick should the triangular object be placed so that the combination of meter stick and rock is in balance?



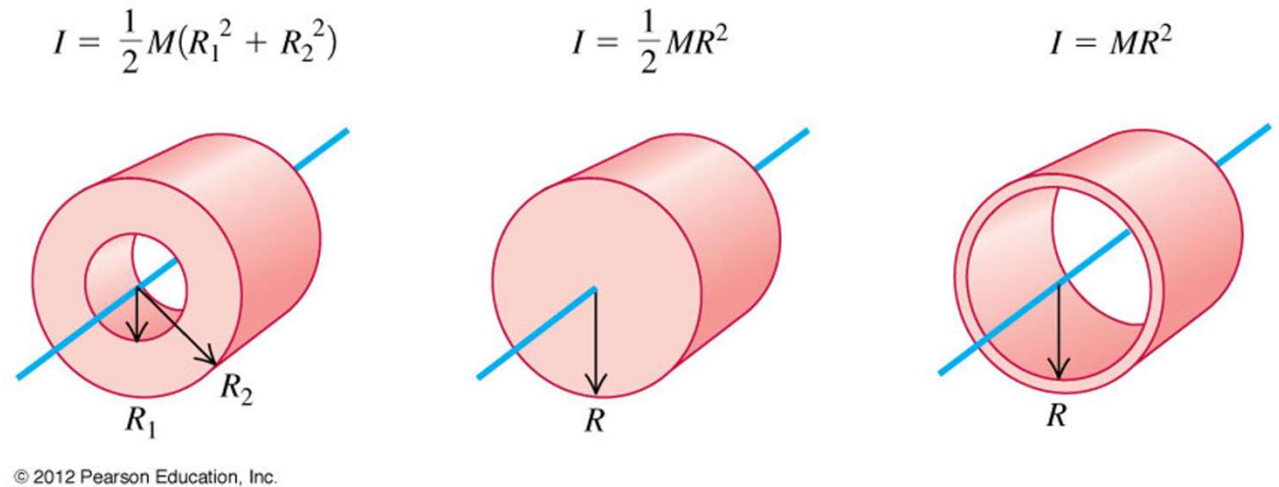
Current picture of location of the support triangle not necessarily shown correctly

- A. less than 0.25 m
- B. 0.25 m
- C. between 0.25 m and 0.50 m
- D. 0.50 m
- E. more than 0.50 m



Q115

The three objects shown here all have the same mass M and radius R . Each object is rotating about its axis of symmetry (shown in blue). All three objects have the *same* rotational kinetic energy. Which one is rotating *fastest*?



- A. thin-walled hollow cylinder
- B. solid sphere
- C. thin-walled hollow sphere
- D. two or more of these are tied for fastest



Q116

Example: A Stellar Performance

A star of radius $R_i = 2.3 \times 10^8$ m rotates initially with an angular speed of $\omega_i = 2.4 \times 10^{-6}$ rad/s.

If the star collapses to a neutron star of radius $R_f = 20.0$ km, what will be its final angular speed ω_f ?

$$L_i = L_f \quad \Rightarrow \quad I_i \omega_i = I_f \omega_f$$

$$\begin{aligned} \omega_f &= \left(\frac{I_i}{I_f} \right) \omega_i = \frac{\frac{2}{5} MR_i^2}{\frac{2}{5} MR_f^2} \omega_i = \left(\frac{R_i}{R_f} \right)^2 \omega_i \\ &= \left[\frac{(2.3 \times 10^8 \text{ m})}{(2.0 \times 10^4 \text{ m})} \right]^2 (2.4 \times 10^{-6} \text{ rad/s}) = 320 \text{ rad/s} \\ &= 3056 \text{ rpm} \end{aligned}$$